11-LEJS Series Page 533

Particle Generation Measuring Method

The particle generation data for 11-LEJS series are measured in the following test method.

■Test Method (Example)

Operate the specimen that is placed in an ISO Class 5 equivalent clean bench, and measure the changes of the particle concentration over time until the number of cycles reaches the specified point.

■ Measuring Conditions

	Description	Laser dust monitor (Automatic particle counter by lightscattering method)
Measuring instrument	Minimum measurable particle diameter	0.1 μm
motrament	Suction flow rate	28.3 L/min (ANR)
a	Sampling time	5 min
Setting conditions	Interval time	55 min
	Sampling air flow	141.5 L (ANR)



Particle generation measuring circuit

■Test Conditions

	Size	Speed [mm/s]	Model	Workpiece mass [kg]	Acceleration [mm/s ²]	Duty ratio [%]
	40	1200	11-LEJS40□A-200		13000	
		600	11-LEJS40□B-200	4	10000	100
Ì	63	1200	11-LEJS63□A-300	4	13000	100
		600	11-LEJS63□B-300		10000	

^{*} Mounting position: Horizontal

■ Evaluation Method

To obtain the measured values of particle concentration, the accumulated value $^{\text{Note 1})}$ of particles captured every 5 minutes, by the laser dust monitor, is converted into the particle concentration in every 1 $\,\text{m}^{\text{s}}.$

When determining particle generation grades, the 95% upper confidence limit of the average particle concentration (average value), when each specimen is operated at a specified number of cycles Note 2) is considered.

The plots in the graphs indicate the 95% upper confidence limit of the average particle concentration of particles with a diameter within the horizontal axis range.

Note 1) Sampling air flow rate: Number of particles contained in 141.5 L (ANR) of air Note 2) Actuator: 1 million cycles

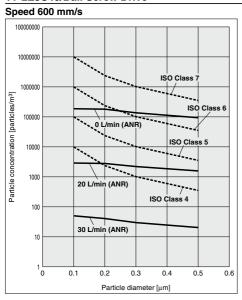
Note 3) The particle generation characteristics (Page 532) provide a guide for selection but is not guaranteed.

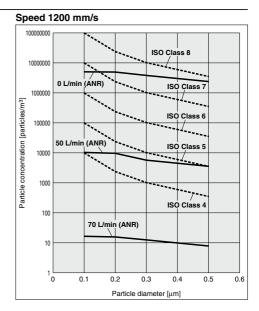




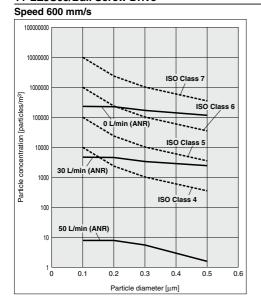
Particle Generation Characteristics

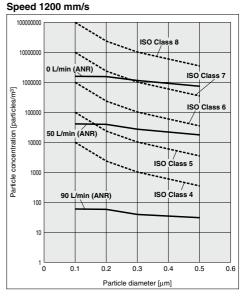
11-LEJS40/Ball Screw Drive





11-LEJS63/Ball Screw Drive





532

Electric Actuator/High Rigidity Slider Type

Ball Screw Drive Clean Room Specification

11-LEJS Series LEJS40. 63

Refer to page 120 for model selection and page 531 for particle generation characteristics.





LECY□ Series Page 534-1

How to Order

11-LE	JS H	40	S2	A-	500			-			
Clean series	T.	4	8		6	6	T	8	9	•	

11 Vacuum type

1 Ac	2 Siz	
Nil	Basic type	40
Н	High precision type	63

A Lead [mm]

Leau [iiiii]					
Symbol	LEJS40	LEJS63			
Α	16	20			
В	8	10			

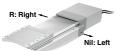
Stroke [mm]*4 200 1500

*4 Refer to the applicable stroke table for details.

6 Motor option Nil Without option With lock

• racaaiii port					
Nil	Left				
R	Right				
D	Both left and right				

*6 Select "D" for the vacuum port for suction of 50 L/min (ANR) or more



200

400 500 600 700 800 900 1000 1200 1500

Applicable Stroke Table*5

Stroke [mm]

Model

Motor type

Symbol	Туре	Output [W]	Actuator size	Compatible driver	UL- compliant
S2*1	AC servo motor (Incremental encoder)	100	40	LECSA□-S1	_
S3	AC servo motor (Incremental encoder)	200	63	LECSA□-S3	-
S6*1	AC servo motor (Absolute encoder)	100	40	LECSB□-S5 LECSC□-S5 LECSS□-S5	-
S7	AC servo motor (Absolute encoder)	200	63	LECSB□-S7 LECSC□-S7 LECSS□-S7	-
T6*2, *3		100	40	LECSB2-T5 LECSC2-T5	_
	AC servo motor			LECSS2-T5	●*3
T7*3	(Absolute encoder)	200	63	LECSB2-T7 LECSC2-T7	_
				LECSS2-T7	●*3

- *1 For motor type S2 and S6, the compatible driver part number suffixes are S1 and S5 respectively.
- *2 For motor type T6, the compatible driver part number suffix is T5. *3 The only compatible drivers complaint with UL standards are the LECSS2-T5 and LECSS2-T7.

_			
8	Cable	tvne*7,	*8

Oubic type					
Nil	Without cable				
S	Standard cable				
R	Robotic cable (Flexible cable)				

*7 The motor and encoder cables are included. (The lock cable is also included when the motor with lock option is selected.)

: Standard

*8 Standard cable entry direction is "(A) Axis side".

Cable length [m]*7, *9

Capic length [m]				
Nil	Without cable			
2	2 m			
5	5 m			
Α	10 m			

*9 The length of the encoder, motor and lock cables are the same.

n Driver type∗6

<u> </u>	vei type -		
	Compatible driver	Power supply voltage [V]	UL-compliant
Nil	Without driver	_	_
A1	LECSA1-S□	100 to 120	_
A2	LECSA2-S□	200 to 230	_
B1	LECSB1-S□	100 to 120	_
B2	LECSB2-S□	200 to 230	_
DZ	LECSB2-T□	200 to 240	_
C1	LECSC1-S□	100 to 120	_
C2	LECSC2-S□	200 to 230	_
62	LECSC2-T□	200 10 230	_
S1	LECSS1-S□	100 to 120	_
S2	LECSS2-S□	200 to 230	_
32	LECSS2-T□	200 to 240	•

*6 When the driver type is selected, the cable is included. Select cable type and cable length.

Example) S2S2: Standard cable (2 m) + Driver (LECSS2)

: Standard cable (2 m) Nil : Without cable and driver

1/O cable length [m]*10

<u> </u>	cable length [m]
Nil	Without cable
Н	Without cable (Connector only
1	1.5

*10 When "Without driver" is selected for driver type, only "Nil: Without cable" can be selected.

Refer to page 624 if I/O cable is required. (Options are shown on page 624.)

*5 Please consult with SMC for non-standard strokes as they are produced as special orders

For auto switches, refer to pages 142 to 144. Compatible Driver

Driver type	Pulse input type/ Positioning type	Pulse input type	CC-Link direct input type	SSCNET III type	Pulse Input Type	CC-Link Direct Input Type	type
Series	LECSA	LECSB	LECSC	LECSS	LECSB-T	LECSC-T	LECSS-T
Number of point tables	Up to 7	_	Up to 255	_	Up to 255	Up to 255 (2 stations occupied)	_
Pulse input	0	0	_	_	0	_	_
Applicable network	_	_	CC-Link	SSCNET Ⅲ	_	CC-Link	SSCNET III/H
Control encoder	Incremental 17-bit encoder	Absolute 18-bit encoder	Absolute 18-bit encoder	Absolute 18-bit encoder	Absolute 22-bit encoder	Absolute 18-bit encoder	Absolute 22-bit encoder
Communication	USB	USB communication,	USB communication,	USB	USB comr	nunication,	USB
function	communication	RS422 communication	RS422 communication	communication	RS422 com	nmunication	communication
Power supply voltage [V]	100 to 1	20 VAC (50/60 Hz),	200 to 230 VAC (5	0/60 Hz)	200 to 240 VAC (50/60 Hz)	200 to 230 VAC (50/60 Hz)	200 to 240 VAC (50/60 Hz)
Reference page				Page 607			

Specifications

11-LEJS40, 63 AC Servo Motor

Model			40S%/T6	11-LEJS63S ³ /T7						
	Stroke [mm] Note 1)			00, 600, 700, 800	300, 400, 500, 600, 700, 800, 900					
	Horizontal			900, 10	00, 1200	1000, 12	00, 1500			
	Work load [kg	1 Note 2)	Horizontal	30	55	45	85			
	WOLK IOAU [Kg)]	Vertical	5	10	10	20			
			Up to 500	1200	600	1200	600			
			501 to 600	1050	520	1200	600			
			601 to 700	780	390	1200	600			
			701 to 800	600	300	930	460			
	Speed Note 3)		801 to 900	480	240	740	370			
	[mm/s]	Stroke range	901 to 1000	390	190	600	300			
S	[iiiiivə]		1001 to 1100	320	160	500	250			
specifications			1101 to 1200	270	130	420	210			
æ			1201 to 1300	_	_	360	180			
₽			1301 to 1400	_	_	310	150			
9			1401 to 1500	_	_	270	130			
	Max. accelera	tion/deceleration		20000 (Refer to	pages 124 and 125 for lin	nit according to work load	d and duty ratio.)			
Actuator	Positioning re	epeatability	Basic type		±0	02				
at	[mm]	-	High precision type	±0.01						
ಕ	Lost motion [Basic type	0.1 or less						
⋖	Lost motion [mm] Note 4)	High precision type	0.05 or less						
	Lead [mm]			16	8	20	10			
	Impact/Vibrat	ion resistance	[m/s ²] Note 5)		50	20	`			
	Actuation typ	е	-	Ball screw						
	Guide type			Linear guide						
	Grease	Ball screw/Lin	ear guide portion	Low particle generation grease						
	Cleanliness c	lass Note 6)		ISO Class 4 (ISO14644-1)						
	Allowable ext	ernal force [N]		20						
		nperature range		5 to 40						
		midity range [%	RH]	90 or less (No condensation)						
	Regeneration			May be required depending on speed and work load. (Refer to page 121.)						
		[W]/Size [mm]		100/	/□40		'□60			
us	Motor type				AC servo motor					
₽					S2, S3: Incremental 17-b					
8	Encoder Note 1	5)			S6, S7: Absolute 18-bit					
뜻	Elicodei	-,			ute 22-bit encoder (Resolu					
ĕ				Motor type T6, T7:	Absolute 18-bit encoder	Resolution: 262144 p/rev	/) (For LECSC-T□)			
<u>s</u>	Bower concur	ntion FMI Note 7)	Horizontal		55		0			
Ĕ	Power consumption [W] Note 7) Vertical				65		35			
Electric specifications		er consumption	Horizontal		2		2			
Ш	when operating [W] Note 8) Vertical			0	12					
	Max. instantar	eous power cor	sumption [W] Note 9)	4-	45	72	25			
T SIIC	Type Note 10) Holding force Power consult Rated voltage 1) Please cons					etizing lock				
eati e	Holding force	[N]		101	203	330	660			
3 5	Power consu	mption [W] at 2	0°C Note 11)	6	.3		.9			
g	Rated voltage	[V]			24 VE	C _10%				
Note	1) Please cons	ult with SMC for	r non-standard strok	es as they are pro- N	lote 7) The power consur	ontion (including the drive	ar) is for when the actua			

Note 1) Please consult with SMC for non-standard strokes as they are produced as special orders. Note 2) Refer to "Speed-Work Load Graph (Guide)" on page 121 for details.

Note 3) The allowable speed changes according to the stroke.

Note 4) A reference value for correcting an error in reciprocal operation.

Note 5) Impact resistance: No malfunction occurred when the actuator was tested with a drop tester in both an axial direction and a perpendicular direction to the lead screw.

(Test was performed with the actuator in the initial state.)

Vibration resistance: No malfunction occurred in a test ranging between 45 to 2000 Hz. Test was performed in both an axial direction and a perpendicular direction to the lead screw. (Test was performed with the aduator in the initial state.)

Note 6) The amount of particle generation changes according to the operating conditions and suction flow rate. Refer to the particle generation characteristics for details. Note 7) The power consumption (including the driver) is for when the actuator is operating.

Note 8) The standby power consumption when operating (including the driver) is for when the actuator is stopped in the set position during the operation.

Note 9) The maximum instantaneous power consumption (including the driver) is for when the actuator is operating. This value can be used for the selection of the power supply.

for the selection of the power supply.

Note 10) Only when motor option "With lock" is selected.

Note 11) For an actuator with lock, add the power consumption for the lock.

Note 12) Sensor magnet position is located in the table center.
For detailed dimensions, refer to "Auto Switch Mounting Position" on page 142.

Note 13) Do not allow collisions at either end of the table traveling distance.

Additionally, when running the positioning operation, do not set within 2 mm of both ends.

Note 14) For the manufacture of intermediate strokes, please contact SMC. (11-LEJS40/Manufacturable stroke range: 200 to 1200 mm, 11-LEJS63/Manufacturable stroke range: 300 to 1500 mm)

Note 15) The resolution will change depending on the driver type.

Weight

Model					11-LE	JS40				
Stroke [mm]	200	300	400	500	600	700	800	900	1000	1200
Product weight [kg]	5.6	6.4	7.1	7.9	8.7	9.4	10.2	11.0	11.7	13.3
Additional weight with lock [kg]					S2: 0.2/S6:	0.3/T6: 0.2				

Model					11-LE	EJS63				
Stroke [mm]	300	400	500	600	700	800	900	1000	1200	1500
Product weight [kg]	11.4	12.7	13.9	15.2	16.4	17.7	18.9	20.1	22.6	26.4
Additional weight with lock [kg]					S3: 0.4/S7:	0.7/T7: 0.4				

Electric Actuator/High Rigidity Slider Type

Ball Screw Drive Clean Room Specification

11-LEJS Series LEJS40, 63

Refer to page 120 for model selection and page 531 for particle generation characteristics.



LEJS63

LECS□ Series Page 533

How to Order

Dimensions are the same as those of the LECS series. For details, refer to page 535 and onwards

4 Lead [mm] Symbol LEJS40

⑤ Stroke [mm]^{∗3} 200

stroke table for details

Compatible driver Power supply voltage [V]

200 to 230

200 to 230

to

1500 *3 Refer to the applicable

Without driver

LECYM2-V□

LECYU2-V□

I/O cable length [m]*10

11-LEJ	S H	40	V6	A-	500		1-[
ies∙	•	2	8	A	6	6 9		0	1	h

Clean serie

11 Vacuum type

Accuracy

Nil	Basic type
Н	High precision type

2 Size	
40	
63	

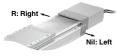
Motor option

•	
Nil	Without option
В	With lock

7 Vacuum port^{≈5}

Nil	Left
R	Right
D	Both left and right

*5 Select "D" for the vacuum port for suction of 50 L/min (ANR) or more.



Compatible Driver

Motor type *1

Symbol	Туре	Output [W]	Actuator size	Compatible*2 driver
V6	AC servo motor (Absolute encoder)	100	40	LECYM2-V5 LECYU2-V5
V7	AC servo motor (Absolute encoder)	200	63	LECYM2-V7 LECYU2-V7

*1 For motor type V6, the compatible driver part number suffix is V5.

*2 For details of the driver, refer to page 607.

8 Cable type*6, *7, *8

Nil	Without cable
S	Standard cable
R	Robotic cable (Flexible cable)

*6 When the driver type is selected, the cable is included. Select cable type and cable length. Example)

S2S2: Standard cable (2 m) + Driver (LECSS2)

S2: Standard cable (2 m)

Without cable and driver

*7 The motor and encoder cables are included. (The lock cable is also included when the motor with lock option is selected.)

*8 Standard cable entry direction is "(A) Axis side".

9 Cable length [m]*6, *9

Nil	Without cable
3	3
5	5
Α	10
С	20

*9 The length of the cables are the same.

encoder, motor and lock

Driver type^{∗6}

U2

*10 When "Without driver" is selected for driver type, only "Nil: Without cable" can be selected.

Without cable

Without cable (Connector only)

Refer to page 624 if I/O cable is required.

(Options are shown on page 624.)

Applicable Stroke lable** •: Standard											
Stroke [mm] Model	200	300	400	500	600	700	800	900	1000	1200	1500
11-LEJS40	•	•	•	•	•	•	•	•	•	•	_
11-LEJS63	_	•	•	•	•	•	•	•	•	•	•

*4 Please consult with SMC for non-standard strokes as they are produced as special orders.

For auto switches, refer to pages 142 to 144.

Compandic Direct								
Driver type	MECHATROLINK-II type	MECHATROLINK-III type						
Series	LECYM	LECYU						
Applicable network	MECHATROLINK-II	MECHATROLINK-Ⅲ						
Control encoder	Absolute 20-bit encoder							
Communication device	USB communication, RS-422 communication							
Power supply voltage [V]	200 to 230 VAC (50/60 Hz)							
Reference page	Page	628-1						



Specifications

AC Servo Motor (100/200 W)

	Model			11-LEJ	S40V6	11-LEJS63V7					
	Stroke [mm	Note 1)		200, 300, 400, 50 900, 100	00, 1200	300, 400, 500, 60 1000, 12	00, 1500				
	Work load [kal Note 2)	Horizontal	30	55	45	85				
	WOIK IOau [kg]	Vertical	5	10	10	20				
			Up to 500	1200	600	1200	600				
			501 to 600	1050	520	1200	600				
			601 to 700	780	390	1200	600				
			701 to 800	600	300	930	460				
	Speed Note 3)	0	801 to 900	480	240	740	370				
	[mm/s]	Stroke range	901 to 1000	390	190	600	300				
2	[IIIIII/5]	range	1001 to 1100	320	160	500	250				
ō			1101 to 1200	270	130	420	210				
cat			1201 to 1300	_	_	360	180				
ij			1301 to 1400	_		310	150				
ě			1401 to 1500	_	_	270	130				
s	Max. accele	ration/decele	eration [mm/s ²]	20000 (Refer to	pages 124 and 125 for lir	nit according to work load	and duty ratio.)				
Actuator specifications	Positioning	repeatability	Basic type	±0.02							
泵	[mm]		High precision type	±0.01							
Ă		. F 1 Note 4)	Basic type	0.1 or less							
	Lost motion	[mm] Note 4)	High precision type		0.05 c	or less					
	Lead [mm]			16	8	20	10				
	Impact/Vibration resistance [m/s ²] Note 5)		50/20								
	Actuation ty	/pe	-	Ball screw							
	Guide type	-		Linear guide							
	Grease	Ball screw/Lir	near guide portion	Low particle generation grease							
	Cleanliness	class Note 6)		ISO Class 4 (ISO14644-1)							
	Operating to	emperature r	ange [°C]	5 to 40							
	Operating h	umidity rang	je [%RH]	90 or less (No condensation)							
	Regenerativ	e resistor		May be required depending on speed and work load. (Refer to page 131-2.)							
ns	Motor outpu	ıt [W]/Size [n	nm]	100/	□40	200/	□60				
Electric specifications	Motor type			AC servo motor (200 VAC)							
ica	Encoder			Absolute 20-bit encoder (Resolution: 1048576 p/rev)							
SCif	Daway aanaum	otion [W] Note 7)	Horizontal	6	5	80					
sbe	Power consum	ption [w] Note 7)	Vertical	16	55	23	35				
<u>0</u>	Standby powe	r consumption	Horizontal	2	2	2					
ct	when operating	g [W] Note 8)	Vertical	1	0	1.	2				
음			umption [W] Note 9)	44	15	72	25				
Lock unit specifications	Type Note 10)				Non-magn	etizing lock					
ate:	Holding for	ce [N]		101	202	162	324				
쓿	Power cons	umption at 2	0°C [W] Note 11)	5.		6	3				
ads	Rated volta	ge [V]			24 VD	C+10%					
	1) Places concult	with SMC for non	standard strokes as th	ev are produced as special orders.	Note 7) The nower consum	nption (including the driver) is for	when the actuator is operating				

Note 1) Please consult with SMC for non-standard strokes as they are produced as special orders. Note 2) Refer to "Speed-Work Load Graph (Guide)" on page 131-2 for details. Note 3) The allowable speed changes according to the stroke. Note 4) A reference value for correcting an error in reciprocal operation.

Note 5) Impact resistance: No malfunction occurred when the actuator was tested with a drop tester in both an axial direction and a perpendicular direction to the lead screw. (Test was

performed with the actuator in the initial state.) Vibration resistance: No malfunction occurred in a test ranging between 45 to 2000 Hz. Test was performed in both an axial direction and a perpendicular direction to the lead screw. (Test was performed with the

actuator in the initial state.) Note 6) The amount of particle generation changes according to the operat-ing conditions and suction flow rate. Refer to the particle generation characteristics for details.

') The power consumption (including the driver) is for when the actuator is operating. Note 8) The standby power consumption when operating (including the driver) is for when the actuator is stopped in the set position during the operation. Note 9) The maximum instantaneous power consumption (including the

driver) is for when the actuator is operating. This value can be used for the selection of the power supply.

Note 10) Only when motor option "With lock" is selected.

Note 11) For an actuator with lock, add the power consumption for the lock. Note 12) Sensor magnet position is located in the table center.

For detailed dimensions, refer to "Auto Switch Mounting Position". Note 13) Do not allow collisions at either end of the table traveling distance. Additionally, when running the positioning operation, do not set within 2 mm of both ends.

Note 14) For the manufacture of intermediate strokes, please contact SMC. (11-LEJS40/Manufacturable stroke range: 200 to 1200 mm, 11-LEJS63/Manufacturable stroke range: 300 to 1500 mm)

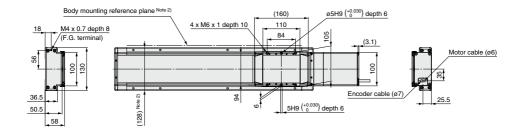
Weight

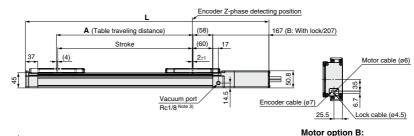
Model		11-LEJS40										
Stroke [mm]	200	300	400	500	600	700	800	900	1000	1200		
Product weight [kg]	5.6	6.4	7.1	7.9	8.7	9.4	10.2	11.0	11.7	13.3		
Additional weight with lock [kg]		0.3 (Absolute encoder)										

Model		11-LEJS63									
Stroke [mm]	300	400	500	600	700	800	900	1000	1200	1500	
Product weight [kg]	11.4	12.7	13.9	15.2	16.4	17.7	18.9	20.1	22.6	26.4	
Additional weight with lock [kg]		0.7 (Absolute encoder)									

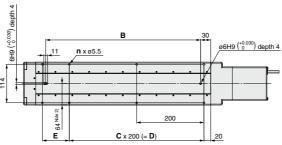
Dimensions: Ball Screw Drive

11-LEJS40





With lock



Note 1) Please consult with SMC for adjusting the Z-phase detecting position at the stroke end of the end side. Note 2) When mounting the actuator using the body mounting reference plane, use a pin. Set the height of the pin to be 5 mm or more because of round chamfering. (Recommended height 6 mm)

Note 3) This drawing shows the left type.

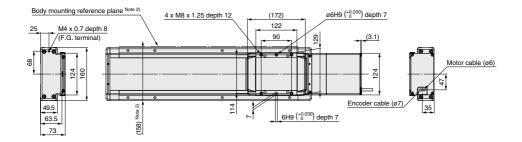
Note 4) The amount of particle generation changes according to the operating conditions and suction flow rate.

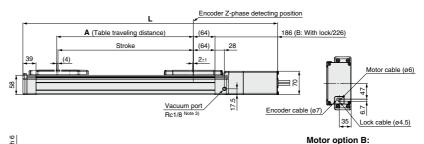
								[mm]
Model	L	L		В	n	С	D	E
Wodel	Without lock	With lock	A	"	"			_
11-LEJS40□□-200□-□□□	523.5	563.5	206	260	6	1	200	80
11-LEJS40 - 300	623.5	663.5	306	360	6	1	200	180
11-LEJS40	723.5	763.5	406	460	8	2	400	80
11-LEJS40 - 500	823.5	863.5	506	560	8	2	400	180
11-LEJS40 -600	923.5	963.5	606	660	10	3	600	80
11-LEJS40 -700	1023.5	1063.5	706	760	10	3	600	180
11-LEJS40□□□-800□□-□□□□	1123.5	1163.5	806	860	12	4	800	80
11-LEJS40□□-900□-□□□	1223.5	1263.5	906	960	12	4	800	180
11-LEJS40 -1000	1323.5	1363.5	1006	1060	14	5	1000	80
11-LEJS40□□-1200□□-□□□□	1523.5	1563.5	1206	1260	16	6	1200	80



Dimensions: Ball Screw Drive

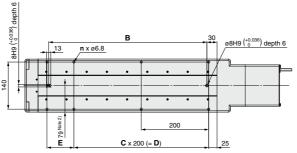
11-LEJS63





With lock

[mm]



Note 1) Please consult with SMC for adjusting the Z-phase detecting position at the stroke end of the end side. Note 2) When mounting the actuator using the body mounting reference plane, use a pin. Set the height of the pin to be 5 mm or more because of round chamfering, (Recommended height 6 mm)

Note 3) This drawing shows the left type.

Note 4) The amount of particle generation changes according to the operating conditions and suction flow rate.

								[mm]
Model	L	L		В	_	С	D	Е
Model	Without lock	With lock A		"	n	0	"	_
11-LEJS63 - 300	656.5	696.5	306	370	6	1	200	180
11-LEJS63 - 400	756.5	796.5	406	470	8	2	400	80
11-LEJS63 - 500	856.5	896.5	506	570	8	2	400	180
11-LEJS63□□-600□□-□□□□	956.5	996.5	606	670	10	3	600	80
11-LEJS63 - 700	1056.5	1096.5	706	770	10	3	600	180
11-LEJS63	1156.5	1196.5	806	870	12	4	800	80
11-LEJS63□□-900□□-□□□□	1256.5	1296.5	906	970	12	4	800	180
11-LEJS631000	1356.5	1396.5	1006	1070	14	5	1000	80
11-LEJS63□□-1200□□-□□□□	1556.5	1596.5	1206	1270	16	6	1200	80
11-LEJS63□□-1500□□-□□□□	1856.5	1896.5	1506	1570	18	7	1400	180