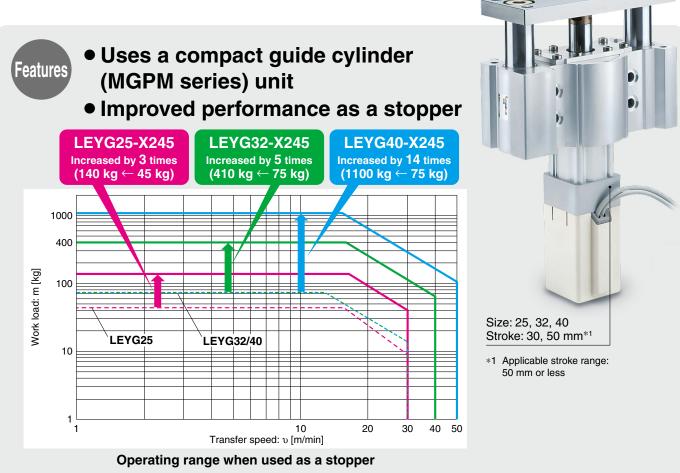
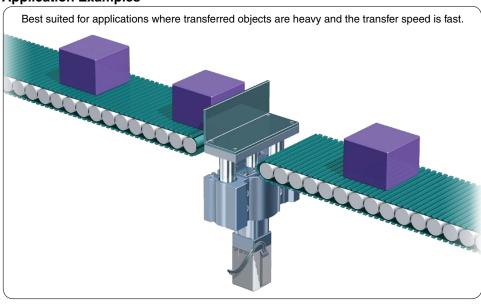
# **Electric Actuator: Guide Rod Type**

LEYG-X245



## **Application Examples**

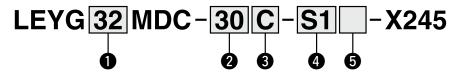


Caution

To ensure the safest possible operation of this product, please be sure to thoroughly read the "Safety Instructions" in our "Best Pneumatics" catalog before use.



#### **How to Order**



Without cable

Standard cable 1.5 m

Standard cable 3 m Standard cable 5 m Robotic cable (Flexible cable) 1.5 m

Robotic cable (Flexible cable) 3 m

Robotic cable (Flexible cable) 5 m

Robotic cable (Flexible cable) 8 m\*1

Robotic cable (Flexible cable) 10 m\*1

Robotic cable (Flexible cable) 15 m\*1

#### 1 Size 25 32

40



With motor cover

With lock/motor cover

_	4 Actuator cable type/length				
1	Nil	Without o			
	S1 Standa				
_	S3	Standard ca			
	S5	Standard ca			
	R1	Robotic cable (Flexit			
	R3	Robotic cable (Flex			
	R5	Robotic cable (Flex			
	R8	Robotic cable (Flexit			

RA

RB

RC

- Robotic cable (Flexible cable) 20 m\*1 \*1 Produced upon receipt of order (Robotic cable only)
- \*2 The standard cable should only be used on fixed parts. For use on moving parts, select the robotic cable.

## 6 Controller/Driver type\*1

<u> </u>				
Nil	Without controller/driver			
6N	LECP6	NPN		
6P	(Step data input type)	PNP		
1N	LECP1	NPN		
1P	(Programless type)	PNP		
MJ	LECPMJ*2	_		
	(CC-Link direct input type)			
AN	LECPA*3	NPN		
AP	(Pulse input type)	PNP		

- \*1 For details on controllers/drivers and compatible motors, refer to the Web Catalog.
- \*2 Not applicable to CE
- \*3 When pulse signals are open collector, order the current limiting resistor (LEC-PA-R-□) separately. (Refer to the Web Catalog.)

## **Specifications**

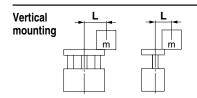
Motor option

No. del				LEVOSENDO VOAS	LEVOCALDO VOAS	LEVO 40MBO VO4E			
				LEYG25MDC-X245 LEYG32MDC-X245 LEYG40MDC-X245					
	Stroke [mm]				30, 50				
		Ial	LECP6 LECP1	(3000 [mm/s <sup>2</sup> ])	60	60	80		
	Work load	Horizontal	LECPMJ	(2000 [mm/s <sup>2</sup> ])	70	80	90		
	[kg]*1	Нoг	LECPA	(3000 [mm/s <sup>2</sup> ])	30	40	60		
				(2000 [mm/s <sup>2</sup> ])	50	60	_		
ရ				(3000 [mm/s <sup>2</sup> ])	30	43	53		
ē	Pushing	Pushing force [N]			232 to 452	296 to 707	562 to 1058		
ca	Speed	LE	CP6/LE	CP1/LECPMJ	5 to 125	6 to 150	6 to 175		
뺼	[mm/s]	LE	СРА		5 to 125	6 to 125	6 to 75		
be	Max. acce	lera	tion/dece	leration [mm/s <sup>2</sup> ]	3000				
S	Pushing	sp	eed [mn	n/s]	35 or less	30 or less	30 or less		
atc	Vertical*2   (3000 [mm/s²])			bility [mm]	±0.02				
댦					0.15 or less				
Ă	Screw le	Screw lead [mm]			3	4	4		
	Impact/Vibration resistance [m/s <sup>2</sup> ]			stance [m/s <sup>2</sup> ]	50/20				
	Actuation type				Ball screw				
	Guide type Operating temperature range [°C]				Sliding bearing				
				ure range [°C]	5 to 40				
	Operating humidity range [%RH]			range [%RH]	90 or less (No condensation)				
	Motor size		□42	□56.4	□56.4				
ations					Step motor (Servo/24 VDC)				
Electric specifications	Encoder				Incremental A/B phase (800 pulse/rotation)				
<u>:</u>	Rated vo	olta	ge [V]		DC24 ±10%				
支	Power consumption [W]			n [W]	40	40 50			
Ee	Standby power consumption when operating [W]		15	48	48				
		Max. instantaneous power consumption [W]			48	104	106		
it ons	Туре				Non-magnetizing lock				
Lock unit	Type Holding force [N] Power consumption [W] Rated voltage [V]				294	421	519		
충블	Power c	ons	sumption	n [W]	5				
as	Rated voltage [V]				DC24 ±10%				
International standards			ndards		CE marking				

- \*1 The maximum value of the work load when the acceleration/deceleration in brackets ( ) is applied
- \*2 The guide weight is not considered in the vertical work load. Add [Guide weight] to the vertical work load, and then refer to the "Speed - Vertical Work Load Graph" of the LEY series in the Web Catalog.
- \*3 For other precautions, refer to the LEY series in the Web Catalog.

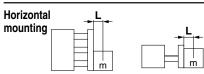
### Weight of Guide Drive

Size	Weight [kg]			
Stroke	25	35	40	
30	0.9	1.6	3.1	
50	1	1.8	3.3	

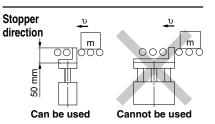


Size	Eccentric distance: L [mm]	10	50	100	200
25	Lood mooo	30	30	21.9	10.9
32	Load mass [kg]	43	43	36	18
40	[49]	53	53	49.2	25

For the load mass, subtract the guide weight according to the stroke.

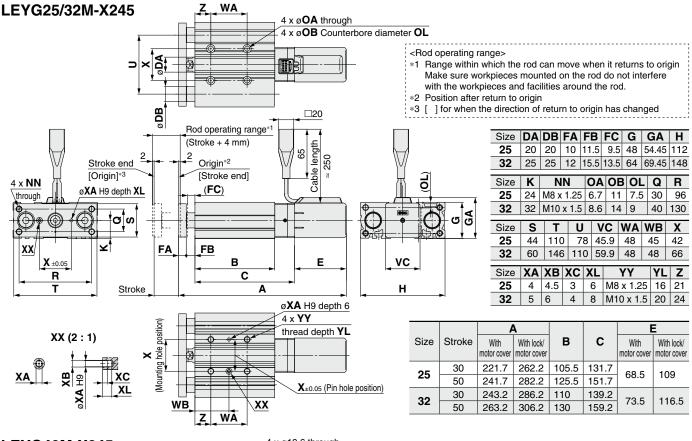


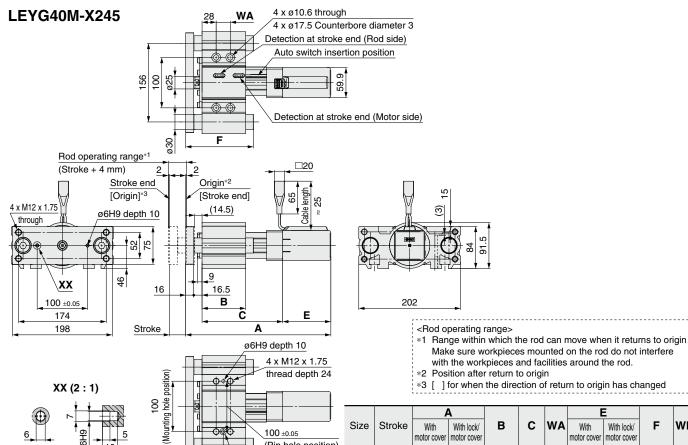
Size	Stroke [mm]	Load mass [kg]		
Size	Stroke [mm]	30	50	
25	L = 50 mm	12.7	11.1	
	L = 100 mm	9.5	8.5	
32	L = 50 mm	19.1	16.7	
	L = 100 mm	14.4	12.9	
40	L = 50 mm	22.5	19.9	
	L = 100 mm	17.2	15.5	





## **Dimensions**





40

30

50

288

331

351

86.5

106.5

(Pin hole position)

WB

WB

F

134.5 42

154.5 54

With lock/

motor cove

138.5

WA

160 28

180 52 With

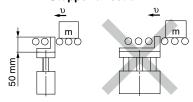
motor cover

95.5

# Caution

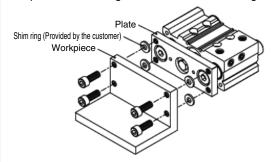
1. Workpiece collision in series with the guide cannot be permitted.

#### Stopper direction



- 2. The manufacturable stroke range is 30 to 300 mm. Please contact SMC for strokes other than 30 and 50. When using as a stopper, select a model with a stroke of 50 mm or less.
- 3. Make sure that the cylinder mounting surface has a flatness of 0.02 mm or less.

If the flatness of the workpieces and brackets mounted on the plate are not appropriate, sliding resistance may increase. If it is difficult to maintain a flatness of 0.02 mm or less, put a thin shim ring (provided by the customer) between the plate and the workpiece mounting surface to prevent the sliding resistance from increasing.



4. Do not scratch or gouge the sliding portion of the piston rod and the guide rod.

Doing so may cause a malfunction.

5. Do not dent or scratch the mounting surface of the body and the plate.

This may cause a decrease in the flatness of the mounting surface, which will cause an increase in sliding resistance.

6. Do not operate the actuator in a state where lateral loads are applied.

The actuator may not operate due to the friction force generated between the conveyor and the transferred object.

Regarding this product, unless otherwise noted along with a separate contract or agreement within the Product Specifications, the safety instructions specified in the catalog are applied.

Please contact your local SMC Sales office for further de-

